Foundation of Intelligent Systems, Part I

Statistical Learning Theory (II)

mcuturi@i.kyoto-u.ac.jp

Previous Lecture : Probabilistic Setting, Loss, Risk

- We observe the outcomes of a pair of random variables (X, Y).
- **Probability P** for couples $(\mathbf{x}, y)$ on $\mathbb{R}^d \times \mathcal{S}$, with density p

$$p(X = \mathbf{x}, Y = y).$$

- **Loss l** to quantify by $l(y, f(\mathbf{x}))$ the accuracy of a guess $f(\mathbf{x})$ for y, $e.g.$

$$\mathcal{S} = \{0, 1\} : \; l(a, b) = \delta_{a \neq b}, \quad \mathcal{S} = \mathbb{R} : \; l(a, b) = \|a - b\|^2$$

- **Risk$_{l,p}(g)$**: average loss for a given function g:

$$R(g) = \mathbb{E}_p[l(Y, g(X))] = \int_{\mathbb{R}^d \times \mathcal{S}} l(y, g(\mathbf{x}))\, p(\mathbf{x}, y) d\mathbf{x} dy$$

Previous Lecture: Bayes Risk, Bayes Classifier/Estimator

- **Bayes Risk**: **lowest** risk over **all possible functions**

$$R^* = \inf_{g \in (\mathbb{R}^d)^{\mathcal{S}}} R(g) = \inf_{g \in (\mathbb{R}^d)^{\mathcal{S}}} \mathbb{E}_p[l(Y, g(X))]$$

- Bayes Classifier (when $\mathcal{S} = \{0, 1\}$):

$$f_B(\mathbf{x}) = \begin{cases} 1, \text{ if } p(Y = 1 | X = \mathbf{x}) \geq \frac{1}{2}, \\ 0 \text{ otherwise.} \end{cases}$$

- Bayes Estimator (when $\mathcal{S} = \mathbb{R}$):

$$f_B(\mathbf{x}) = \mathbb{E}[Y | X = \mathbf{x}] = \int_{\mathbb{R}} y \, p(Y = y, X = \mathbf{x}) dy$$

The **Bayes** classifier/estimator achieve the **Bayes Risk**
for classification with $0 - 1$ loss / regression with squared error
$R(f_B) = R^*$

Previous Lecture: Empirical Risk

- In practice, no access to P. The only thing we can use is a training set,

$$\{(\mathbf{x}_i, y_i)\}_{i=1,\cdots,n}.$$

- Assuming the sampling is i.i.d, a counterpart to the Risk is

$$R_n^{\text{emp}}(g) = \frac{1}{n}\sum_{i=1}^{n} l(y_i, g(\mathbf{x}_i)) \ldots \text{ compare with } R(g) = \mathbb{E}_p[l(Y, g(X))]$$

- What is overfitting?
  - Choose g_n, the best function in a class of functions $\mathcal{G}$ w.r.t R_n^{emp},

$$R_n^{\text{emp}}(g_n) = \min_{g \in \mathcal{F}} R_n^{\text{emp}}(g),$$

  - find out (later!) that, unfortunately, $R_n^{\text{emp}}(g_n) \ll R(g^\star)$.

overfitting: rely blindly on R_n^{emp} when looking for a function with low R.

Previous Lecture: Excess Risk

- For any candidate set of functions $\mathcal{G}$,
- We introduce $g^\star$ as a function achieving the lowest risk in $\mathcal{G}$,

$$R(g^\star) = \inf_{g \in \mathcal{G}} R(g),$$

- Note that $g^\star$ depends on p, **which we do not have access to.**
- Useful however to decompose

$$R(g_n) - R(f_B) = \underbrace{[\boldsymbol{R(g_n) - R(g^\star)}]}_{\textbf{Estimation Error}} + \underbrace{[\boldsymbol{R(g^\star) - R(f_B)}]}_{\textbf{Approximation Error}}$$

Bounds

An overdue definition

Definition of "Empirical"

1. derived from or relating to experiment and observation rather than theory

2. Guided by practical experience and not theory

$$R_n^{\text{emp}}(g) = \frac{1}{n}\sum_{i=1}^{n} l(y_i, g(\mathbf{x}_i)) \text{ vs. } R(g) = \mathbb{E}_p[l(Y, g(X))]$$

Alleviating Notations in the Binary Case

- More convenient to see a couple $(\mathbf{x}, y)$ as a realization of Z, namely

$$\mathbf{z}_i = (\mathbf{x}_i, y_i), Z = (X, Y).$$

Alleviating Notations in the Binary Case

- More convenient to see a couple $(\mathbf{x}, y)$ as a realization of Z, namely

$$\mathbf{z}_i = (\mathbf{x}_i, y_i), Z = (X, Y).$$

- Define the ***loss class***

$$\mathcal{F} = \{f : \mathbf{z} = (\mathbf{x}, y) \to \delta_{g(\mathbf{x}) \neq y},\ g \in \mathcal{G}\},$$

Alleviating Notations in the Binary Case

- More convenient to see a couple $(\mathbf{x}, y)$ as a realization of Z, namely

$$\mathbf{z}_i = (\mathbf{x}_i, y_i), Z = (X, Y).$$

- Define the ***loss class***

$$\mathcal{F} = \{f : \mathbf{z} = (\mathbf{x}, y) \to \delta_{g(\mathbf{x}) \neq y},\ g \in \mathcal{G}\},$$

- use simpler notations:

$$Pf = \mathbb{E}_{p}[f(X, Y)], \quad P_n f = \frac{1}{n} \sum_{i=1}^{n} f(\mathbf{x}_i, y_i),$$

where we recover

$$Pf = R(g), \quad P_n f = R_n^{\text{emp}}(g)$$

Empirical Processes

For each $f \in \mathcal{F}$, $P_n f$ is a **random variable**
which depends on a **random** sample $\{\mathbf{z}_i = (\mathbf{x}_i, y_i)\}_{i=1\cdots,n}$ of $Z = (X, Y)$.

Empirical Processes

For each $f \in \mathcal{F}$, $P_n f$ is a **random variable**
which depends on a **random** sample $\{\mathbf{z}_i = (\mathbf{x}_i, y_i)\}_{i=1\cdots,n}$ of $Z = (X, Y)$.

- P is a **deterministic** function of **functions in $\mathcal{F}$**.
- P_n is a **random function** of **functions in $\mathcal{F}$**.

Empirical Processes

For each $f \in \mathcal{F}$, $P_n f$ is a **random variable**
which depends on a **random** sample $\{\mathbf{z}_i = (\mathbf{x}_i, y_i)\}_{i=1\cdots,n}$ of $Z = (X, Y)$.

- P is a **deterministic** function of **functions in $\mathcal{F}$**.
- P_n is a **random function** of **functions in $\mathcal{F}$**.
- If we consider P_n on **all** possible functions $f \in \mathcal{F}$, we obtain

The set of random variables $\{P_n f\}_{f \in \mathcal{F}}$ is called an
Empirical measure indexed by $\mathcal{F}$.

Empirical Processes

For each $f \in \mathcal{F}$, $P_n f$ is a **random variable**
which depends on a **random** sample $\{\mathbf{z}_i = (\mathbf{x}_i, y_i)\}_{i=1\cdots,n}$ of $Z = (X, Y)$.

- P is a **deterministic** function of **functions in** $\mathcal{F}$.
- P_n is a **random function** of **functions in** $\mathcal{F}$.
- If we consider P_n on **all** possible functions $f \in \mathcal{F}$, we obtain

The set of random variables $\{P_n f\}_{f \in \mathcal{F}}$ is called an
Empirical measure indexed by $\mathcal{F}$.

- A branch of mathematics studies explicitly the convergence of $\{Pf - P_n f\}_{f \in \mathcal{F}}$,

This branch is known as Empirical process theory.

Hoeffding's Inequality

- Recall that for a given g and corresponding f,

$$R(g) - R^{\text{emp}}(g) = Pf - P_n f = \mathbb{E}[f(Z)] - \frac{1}{n}\sum_{i=1}^{n} f(\mathbf{z}_i),$$

  $\rightarrow$ **difference** between the **expectation** and the **empirical average** of $f(Z)$.

- The **strong** law of large numbers says that

$$P\left(\lim_{n\to\infty}\left(\mathbb{E}[f(Z)] - \frac{1}{n}\sum_{i=1}^{n} f(\mathbf{z}_i)\right) = 0\right) = 1.$$

Hoeffding's Inequality (1963)

Theorem 1 (Hoeffding). *Let $Z_1, \cdots, Z_n$ be n i.i.d random variables with $f(Z) \in [a, b]$. Then, $\forall \varepsilon > 0$,*

$$P\left(|P_n f - Pf| > \varepsilon\right) \leq 2e^{-\frac{2n\varepsilon^2}{(b-a)^2}}.$$

- From

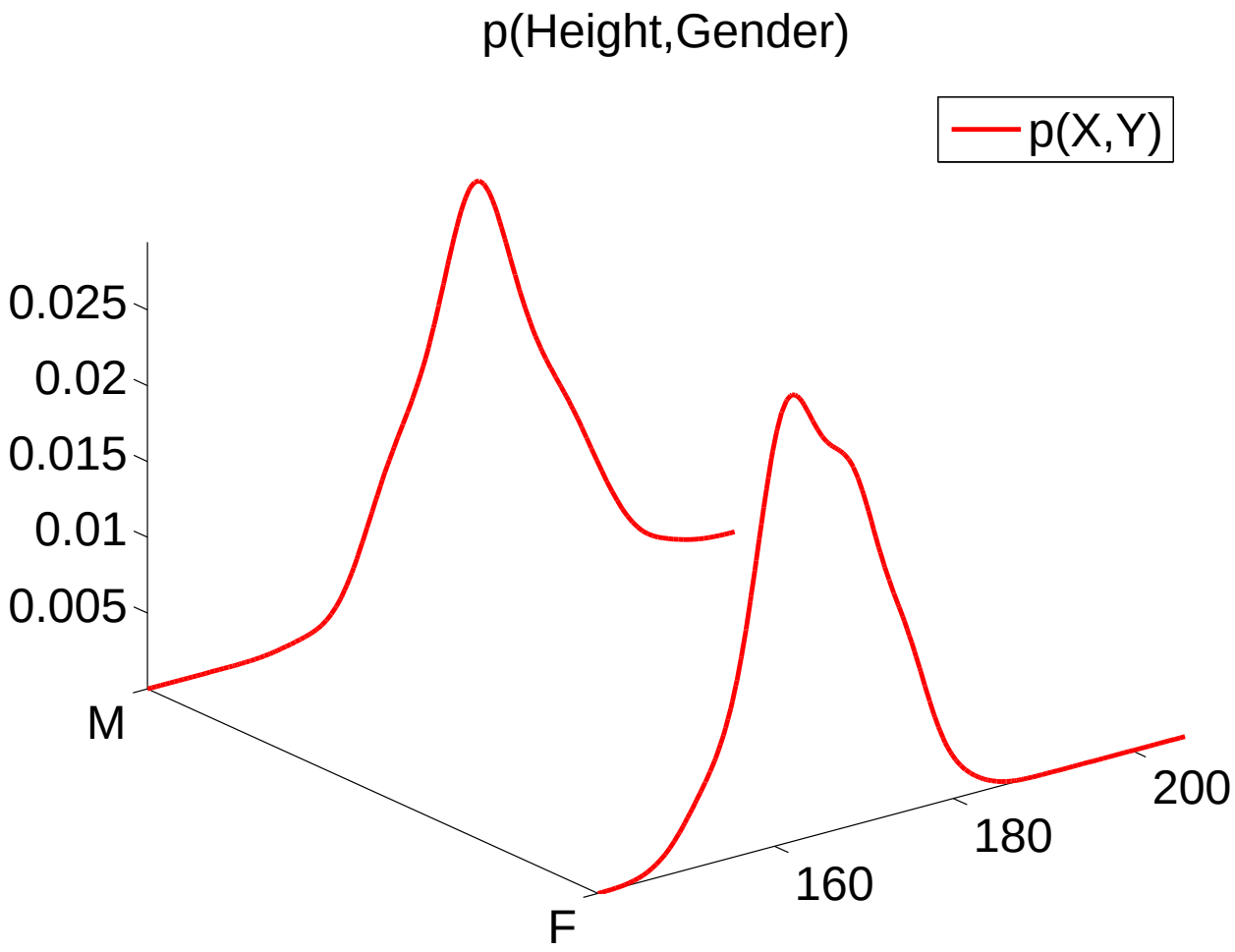
$$P\left(\lim_{\boldsymbol{n\to\infty}} \left(\mathbb{E}[f(Z)] - \frac{1}{n}\sum_{i=1}^{n} f(\mathbf{z}_i)\right) = 0\right) = 1.$$

  we get

$$P\left(\left|\mathbb{E}[f(Z)] - \frac{1}{n}\sum_{i=1}^{n} f(\mathbf{z}_i)\right| > \varepsilon\right) \leq 2e^{-\frac{2\boldsymbol{n}\varepsilon^2}{(b-a)^2}}.$$

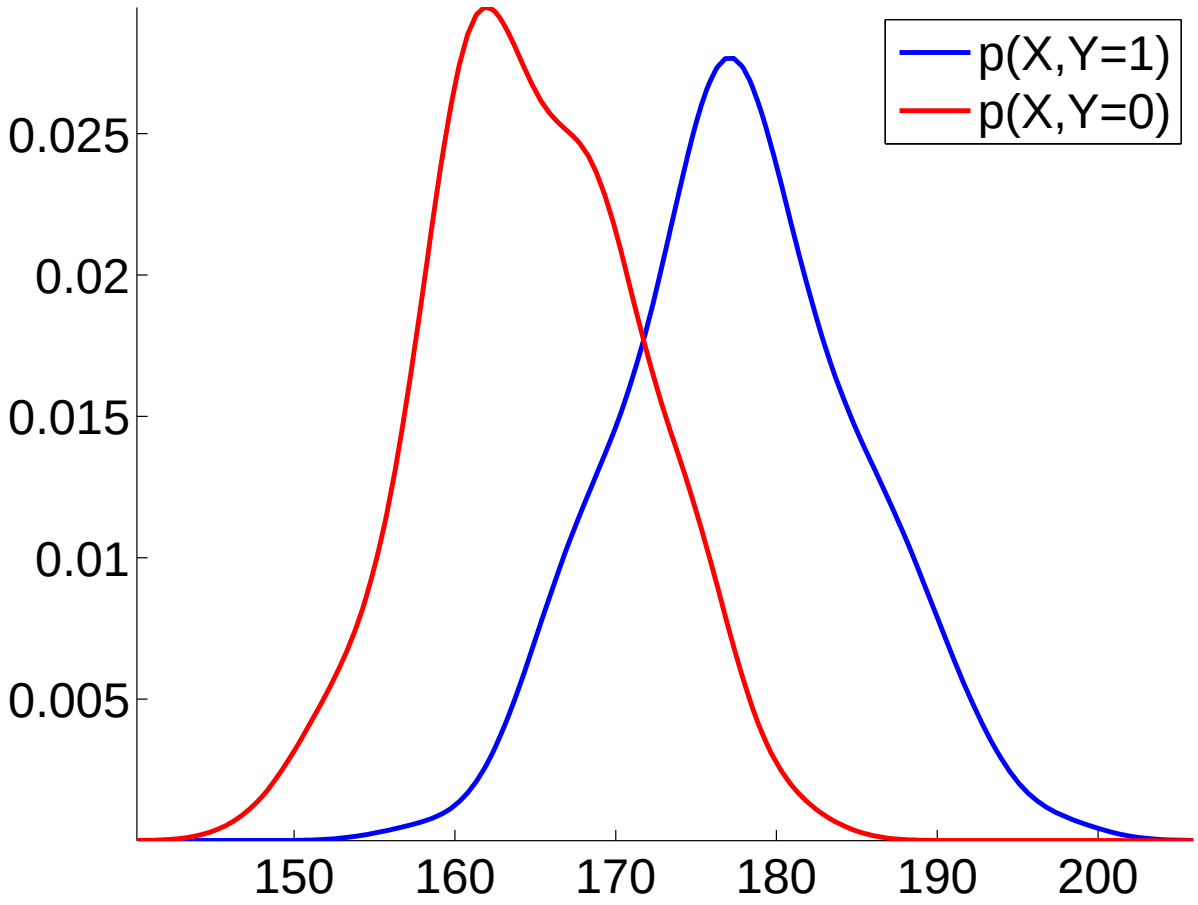
- Hoeffding's inequality is a **concentration inequality**.

Some Intuitions: the Height/Gender problem



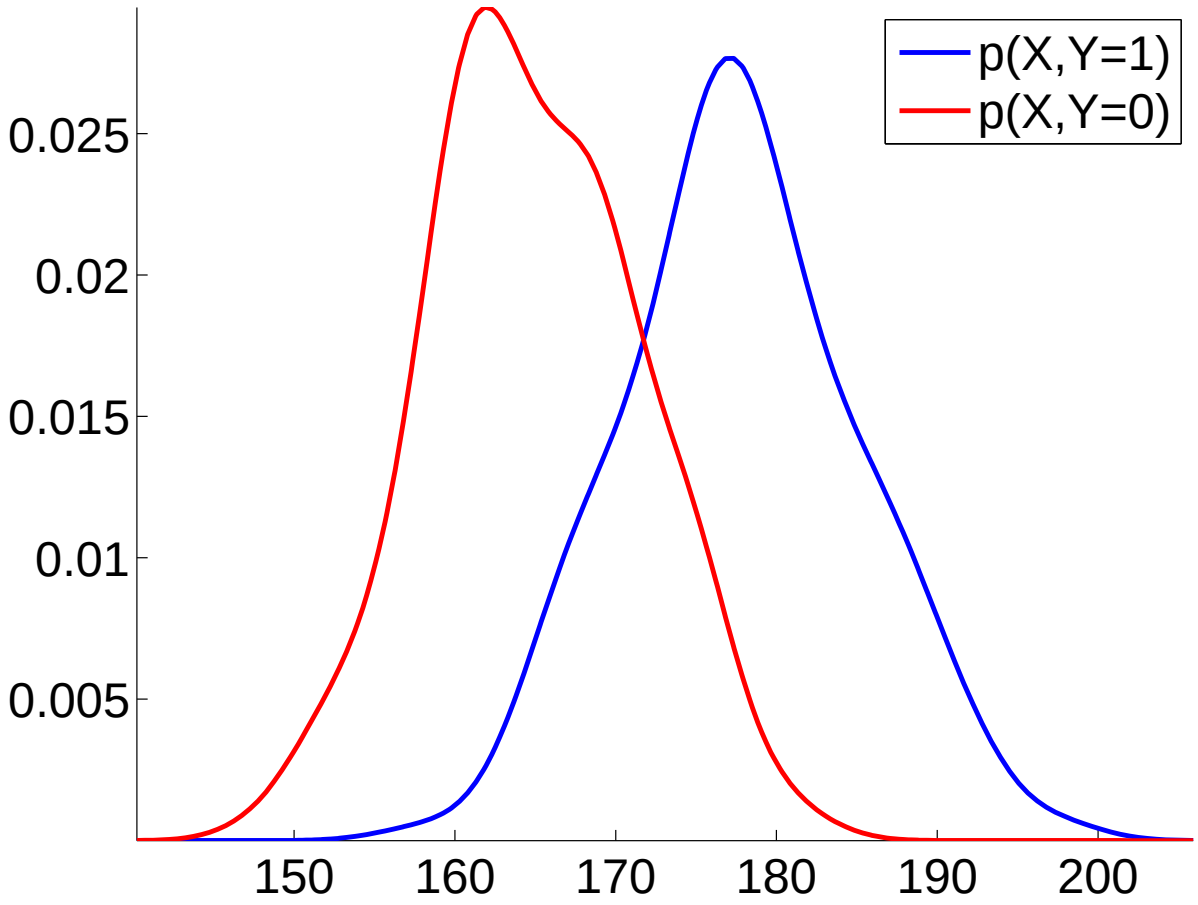
In 3 dimensions

Height/Gender



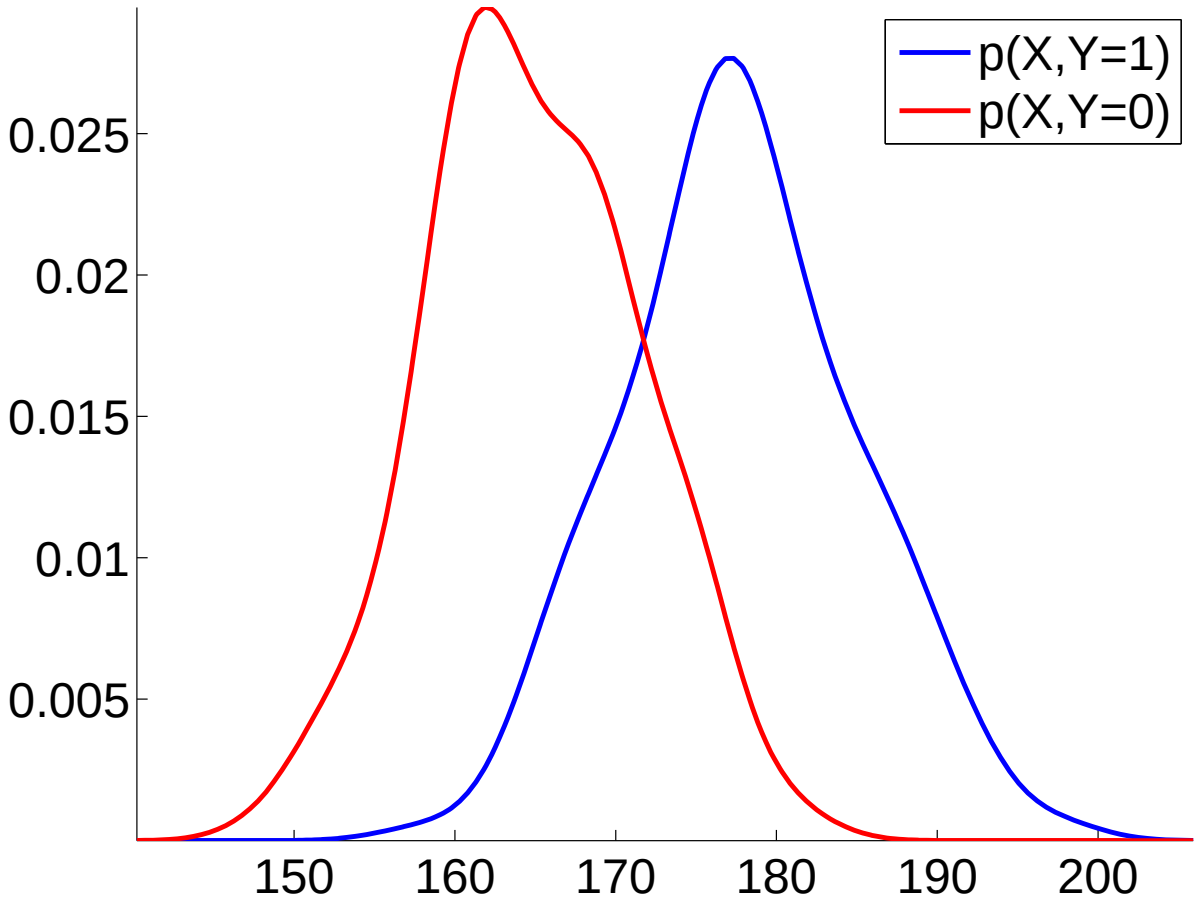
Easier to see in 2 dimensions, same content.

Height/Gender



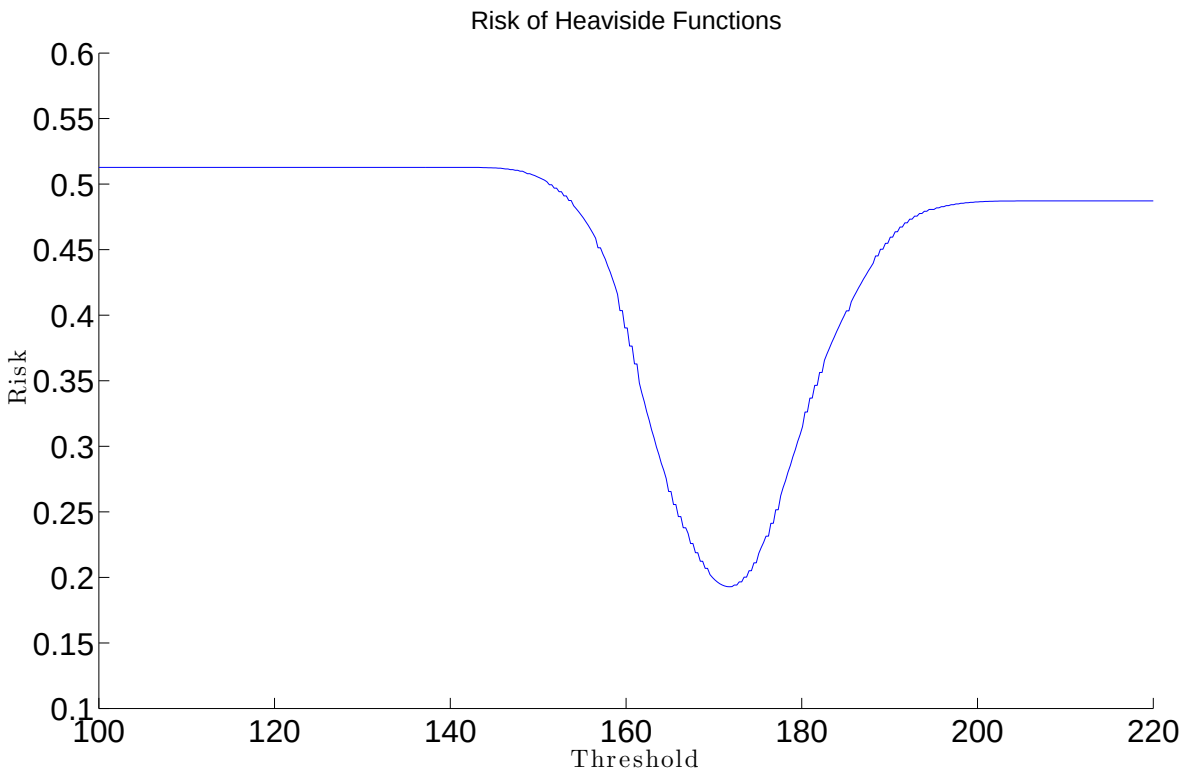
Assume for a minute that we **known** these two curves.

Height/Gender



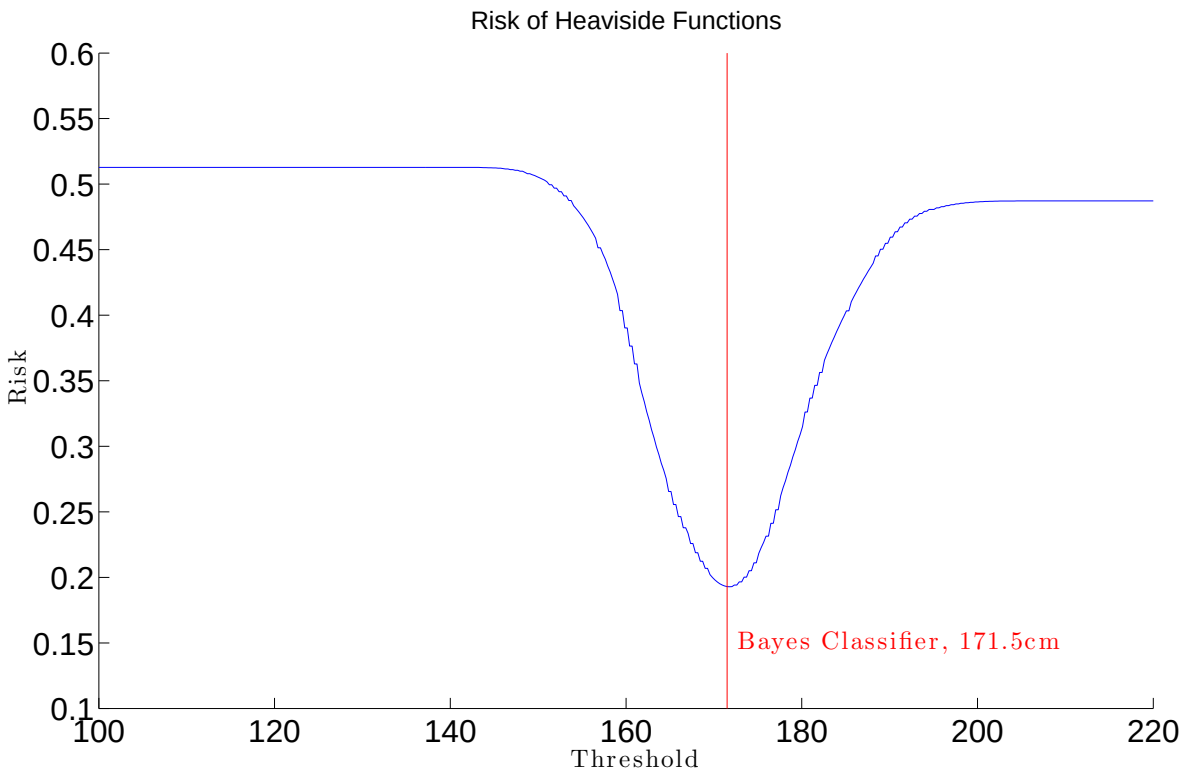
For any function f : Height $\mapsto$ Gender we can compute the risk

Height/Gender



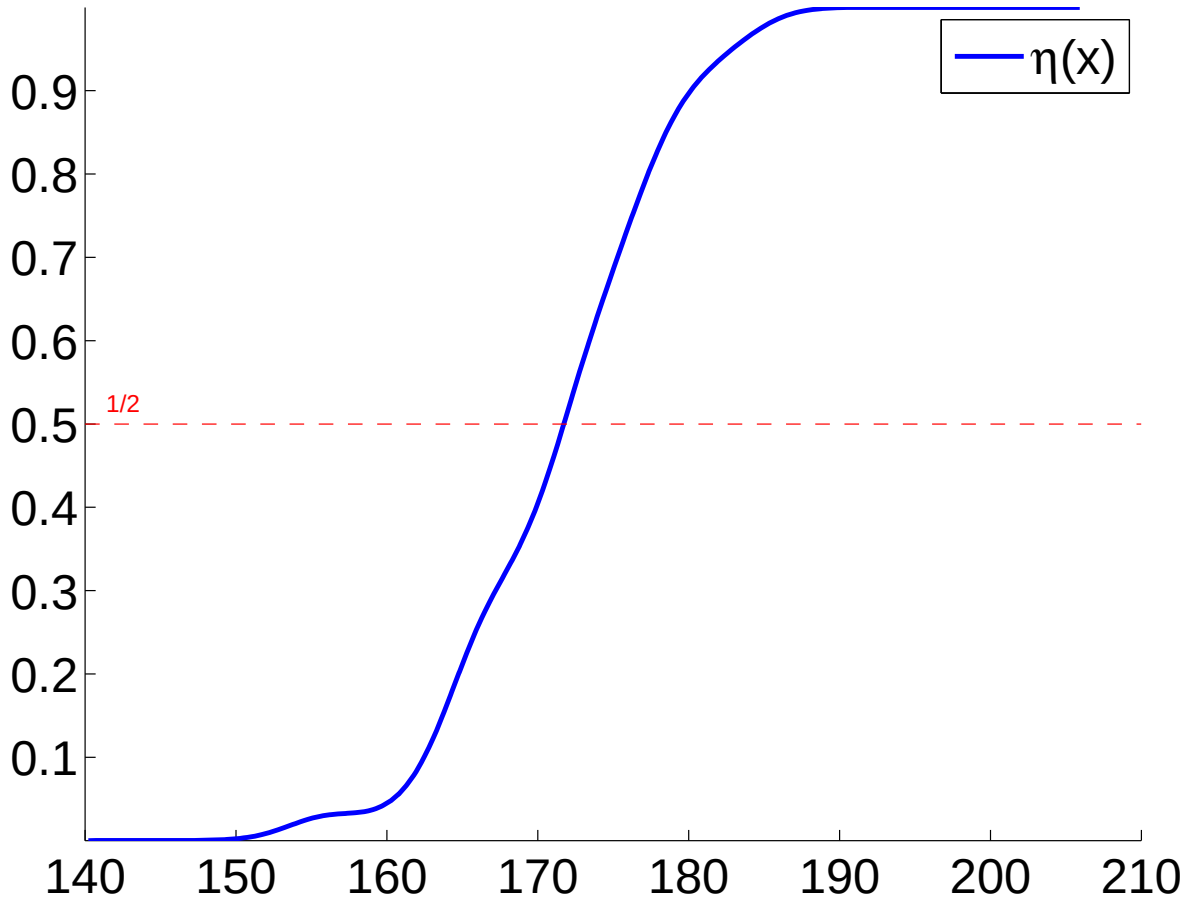
Risk for Heaviside functions $f(x) = \delta_{x>\tau}$

Height/Gender



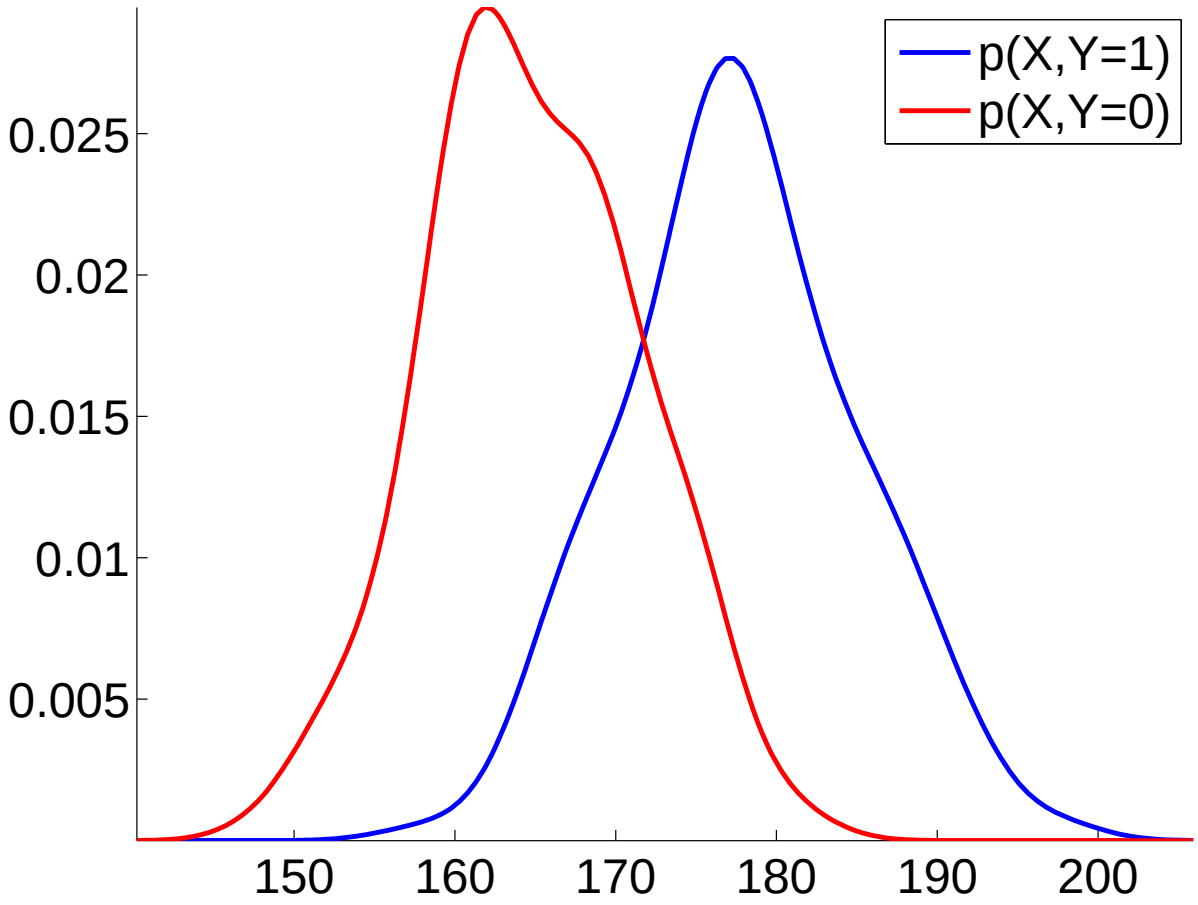
The risk is minimal for the thresholded function with $\tau \approx 171.5$

Height/Gender



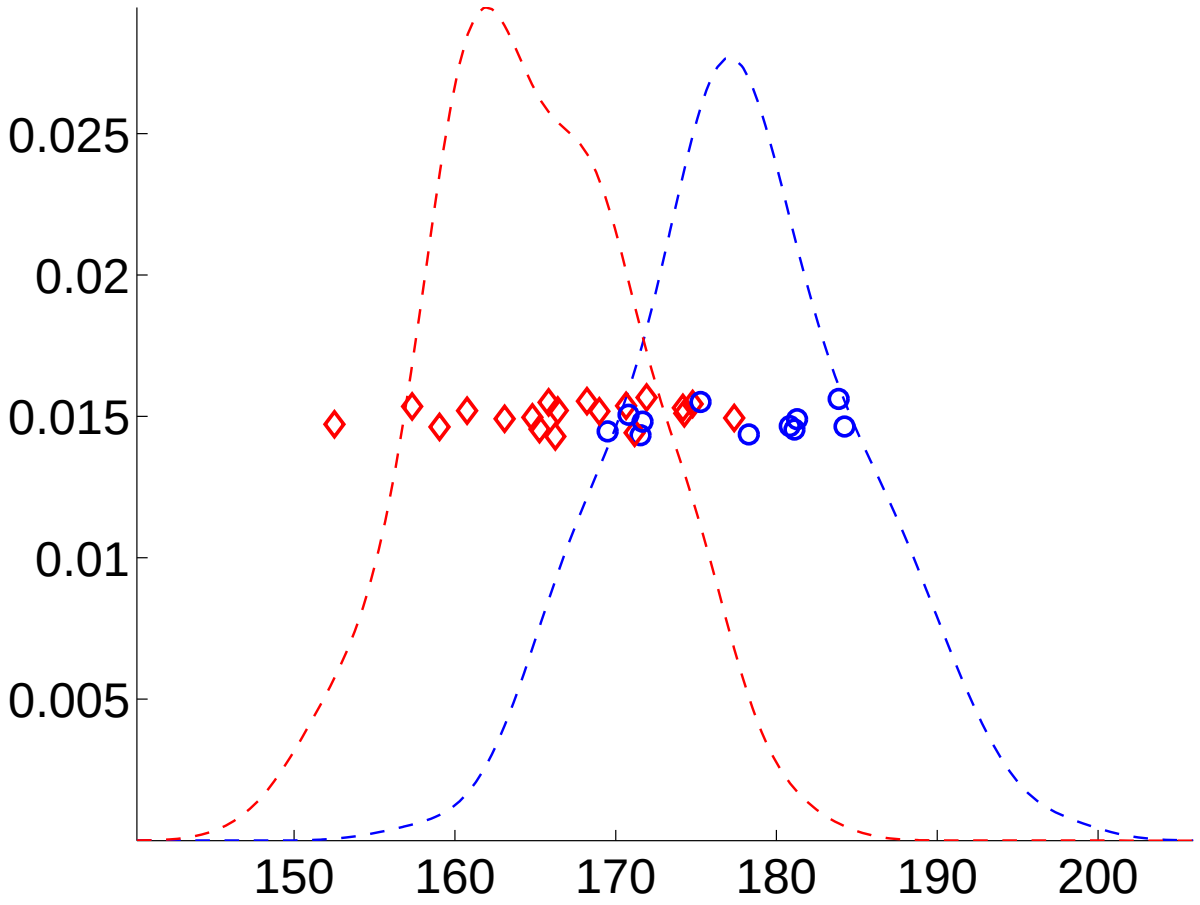
which matches our picture of the Bayes classifier and the $\eta(x) = P(Y = 1|X = \mathbf{x})$ function.

Height/Gender



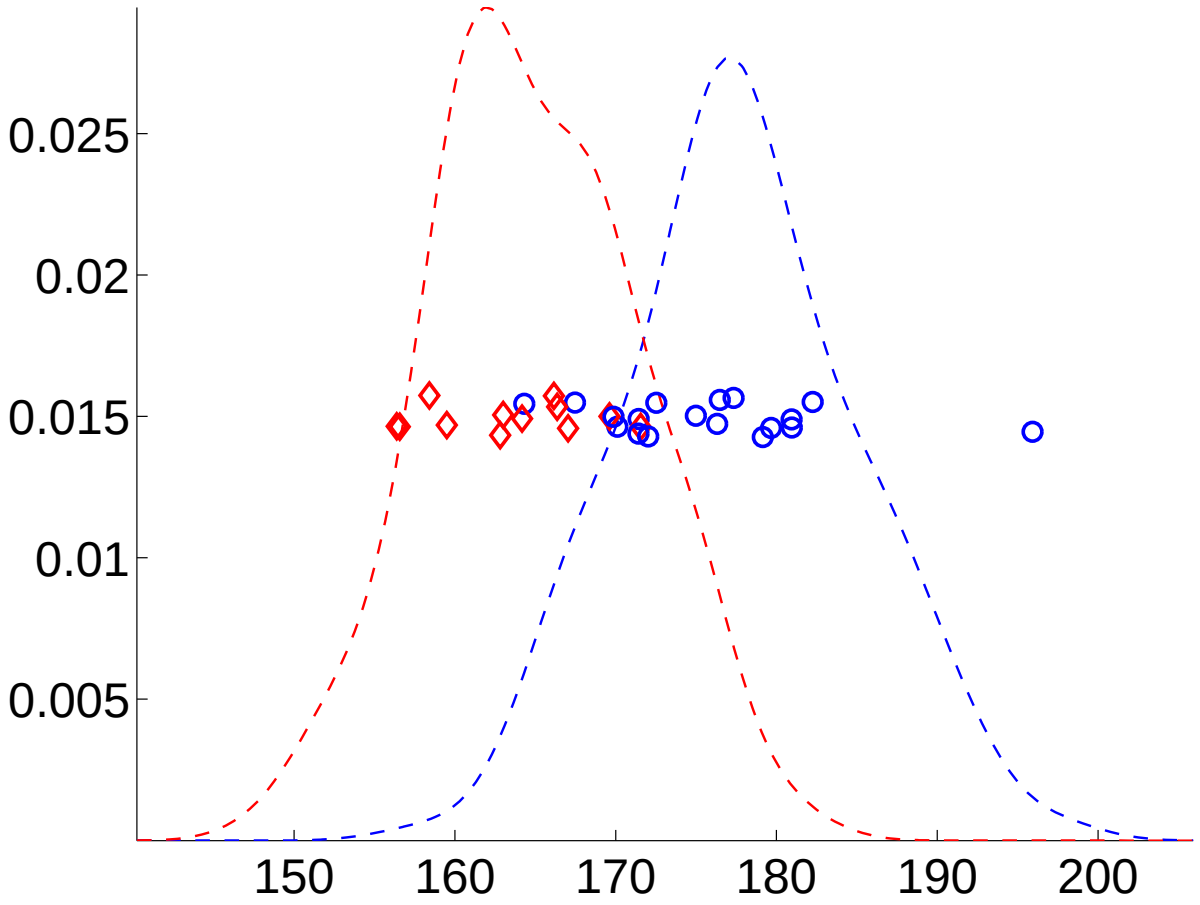
Unfortunately, we do not have access to this,

Height/Gender



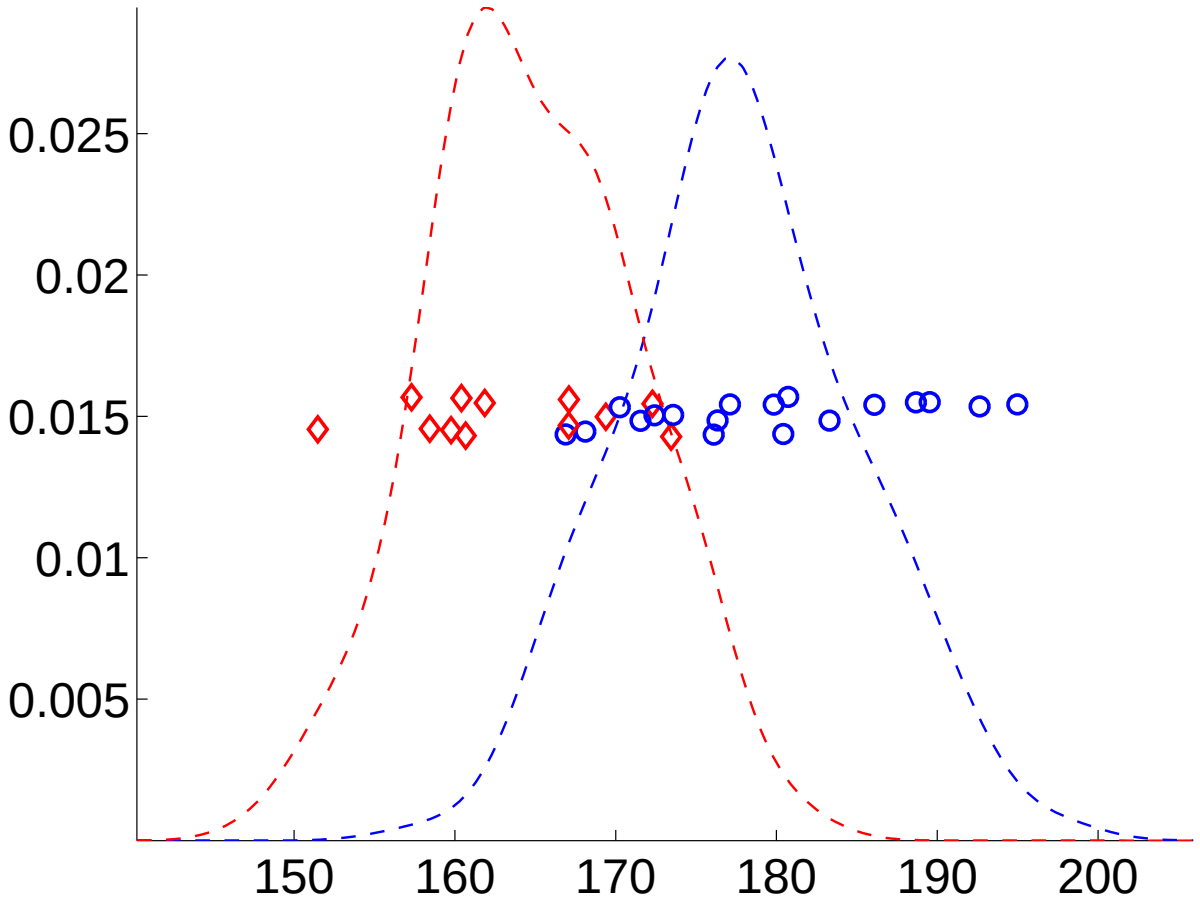
But rather this...

Height/Gender



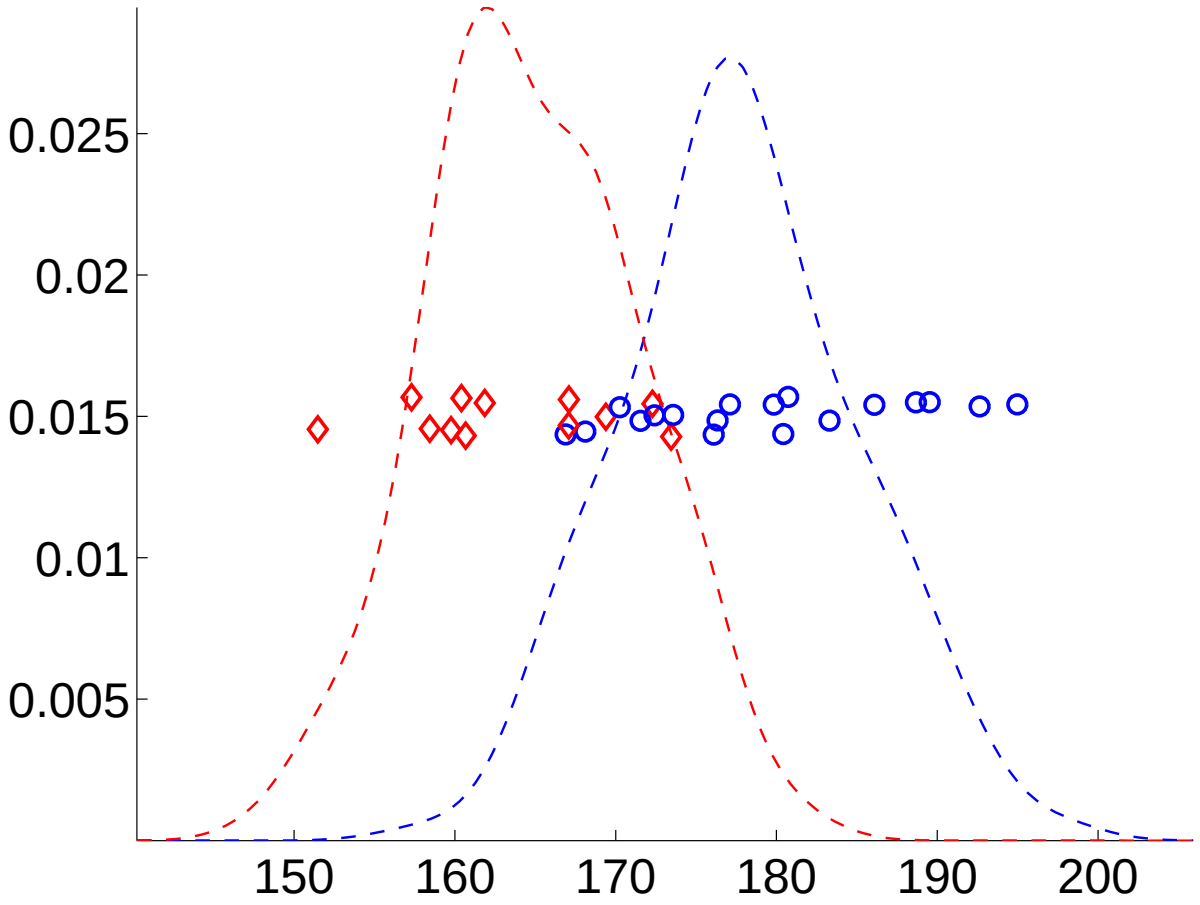
or this...

Height/Gender



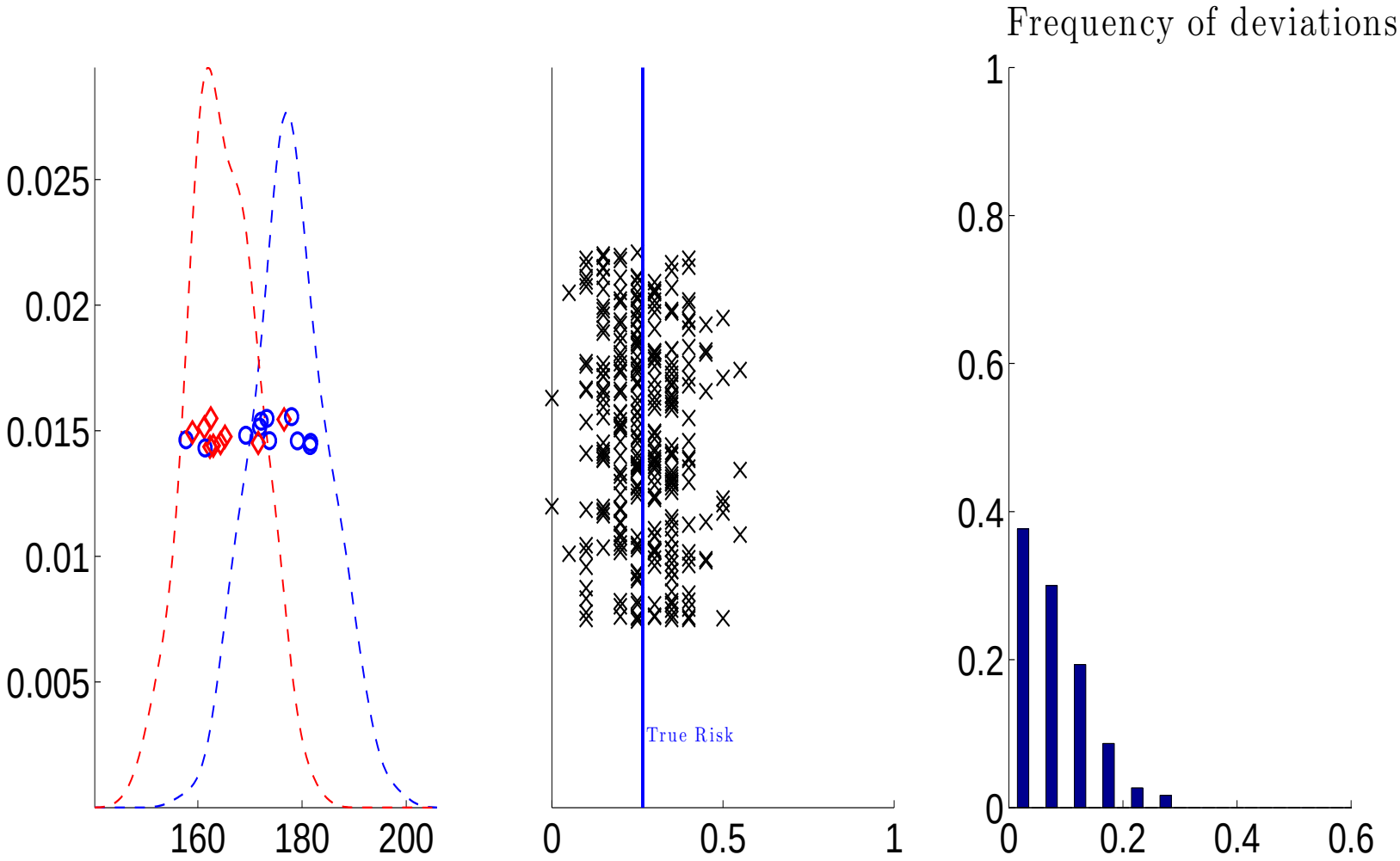
or even this... we assume our samples are **random**.

Height/Gender



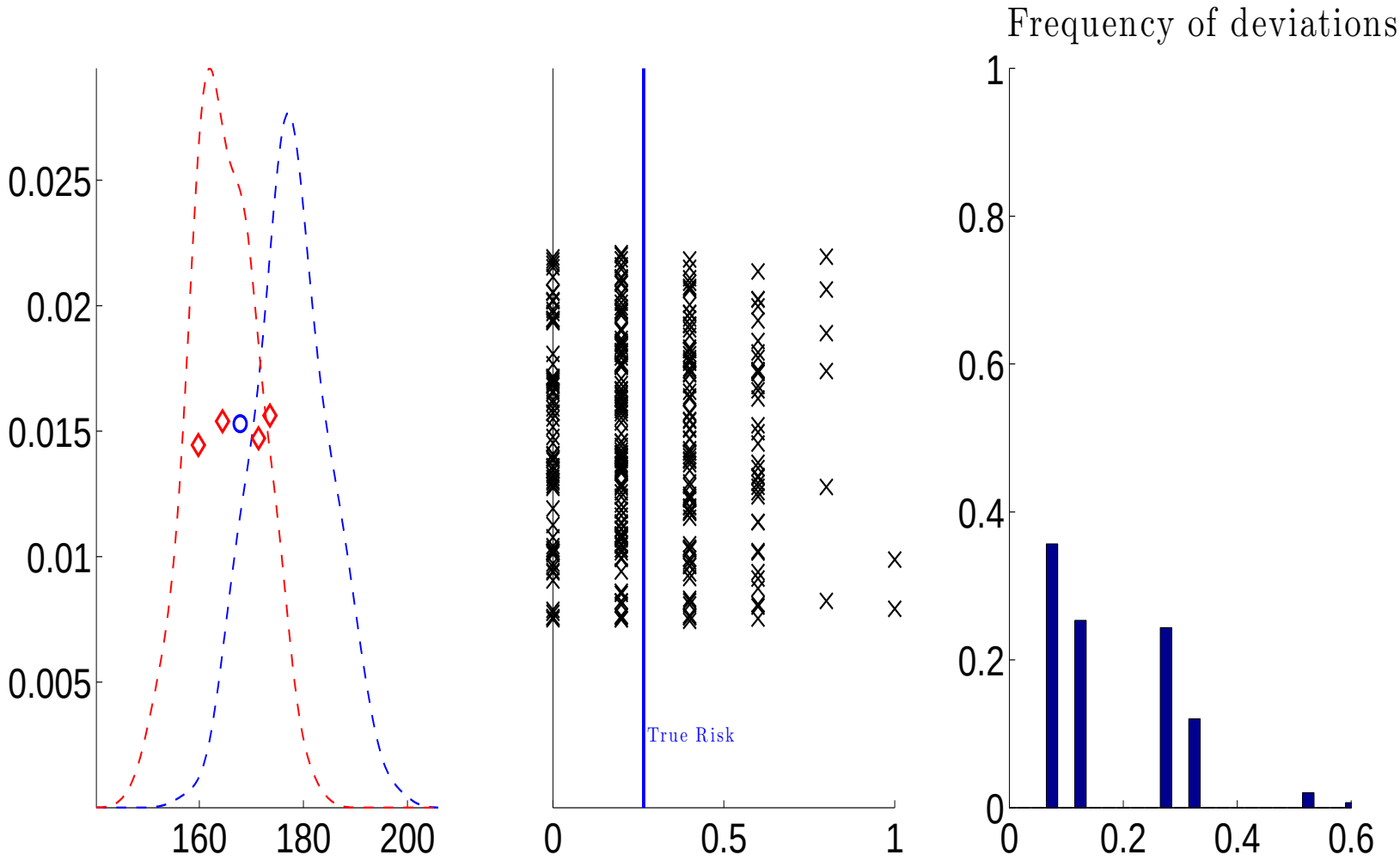
Hoeffding's Inequality: $P\left(|P_n f - Pf| > \varepsilon\right) \leq 2e^{-\frac{2n\varepsilon^2}{(b-a)^2}}$.

Hoeffding's Inequality



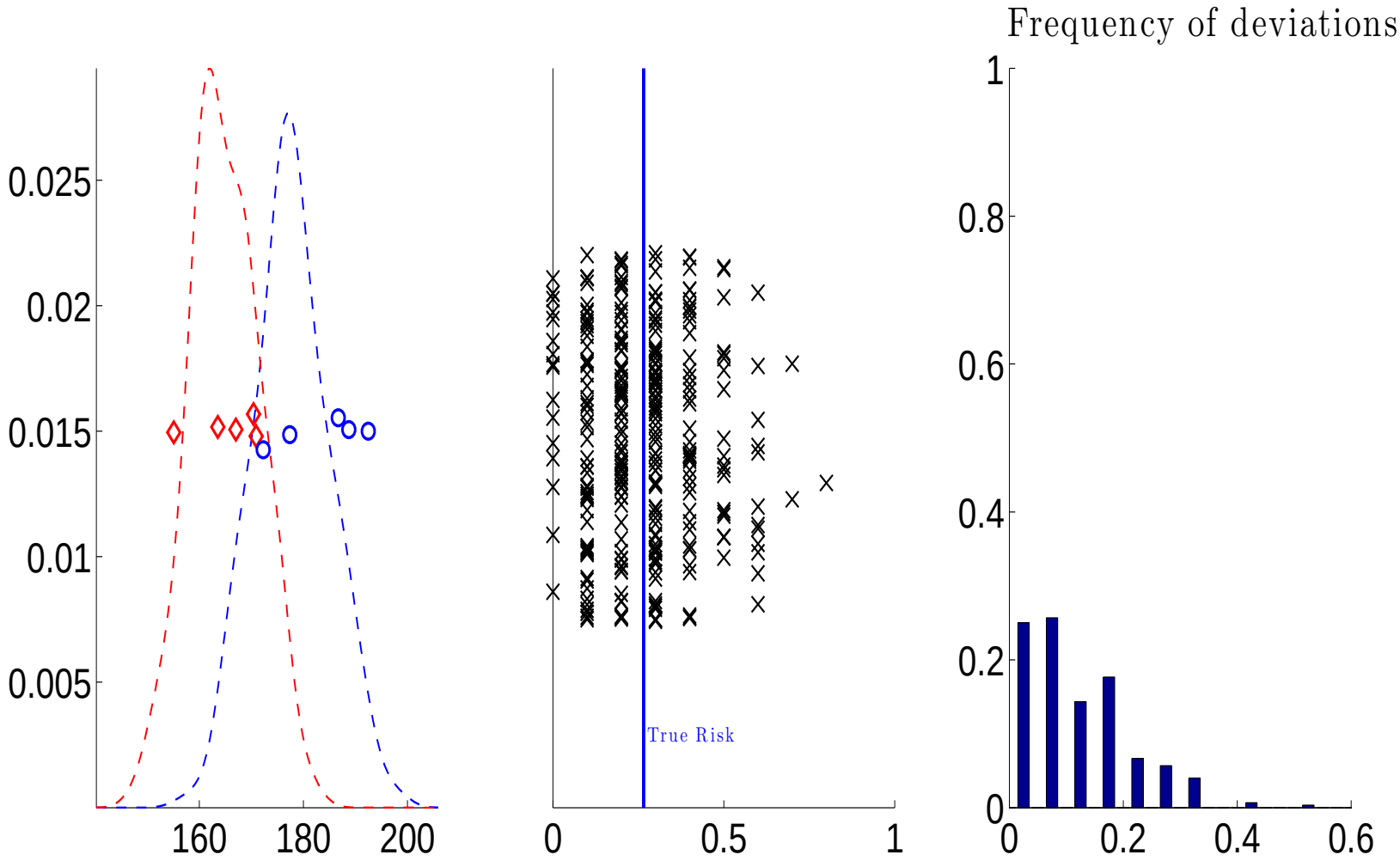
Let's check on Matlab what this means

Hoeffding's Inequality



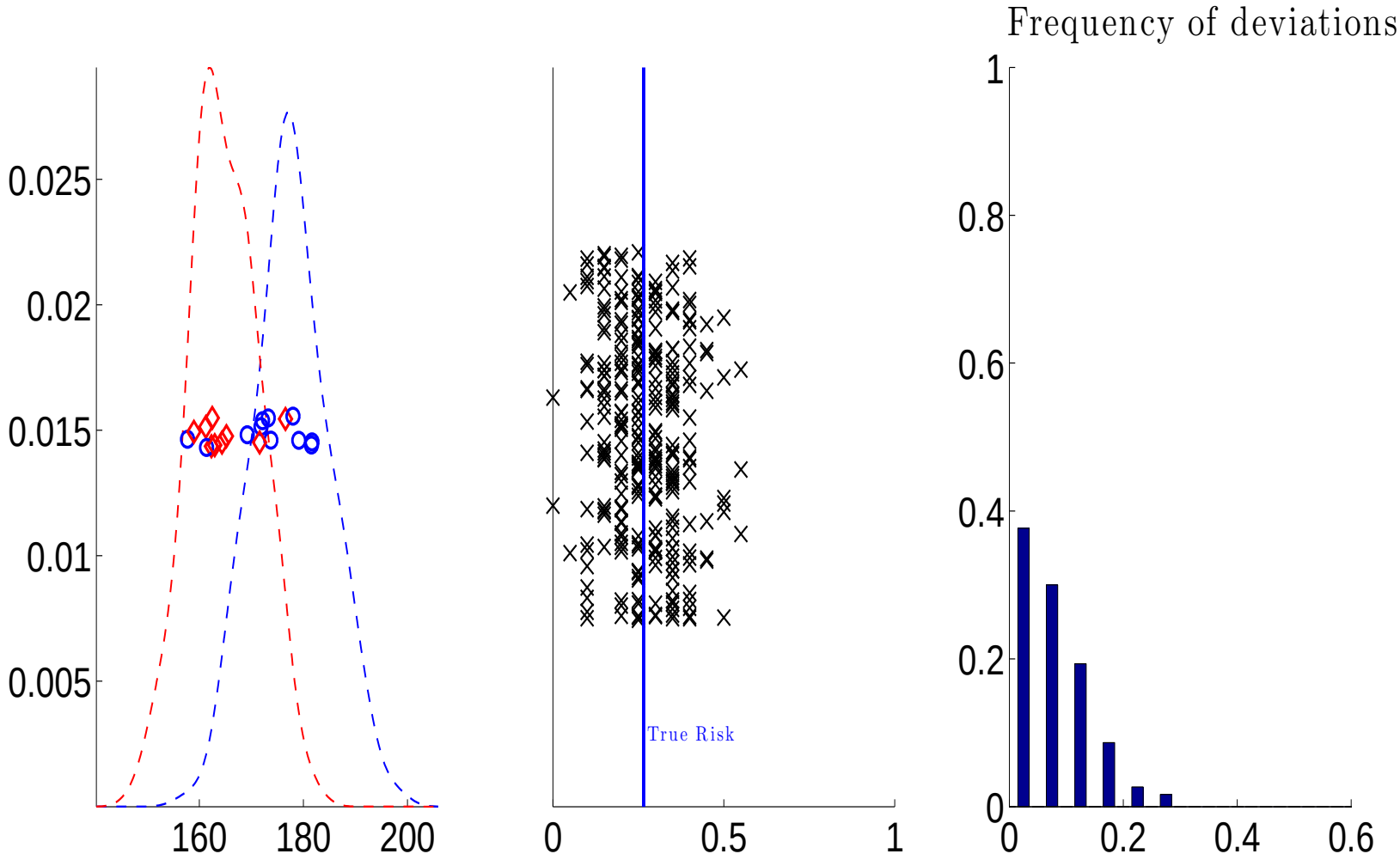
with $n = 5$ resampled 300 times

Hoeffding's Inequality



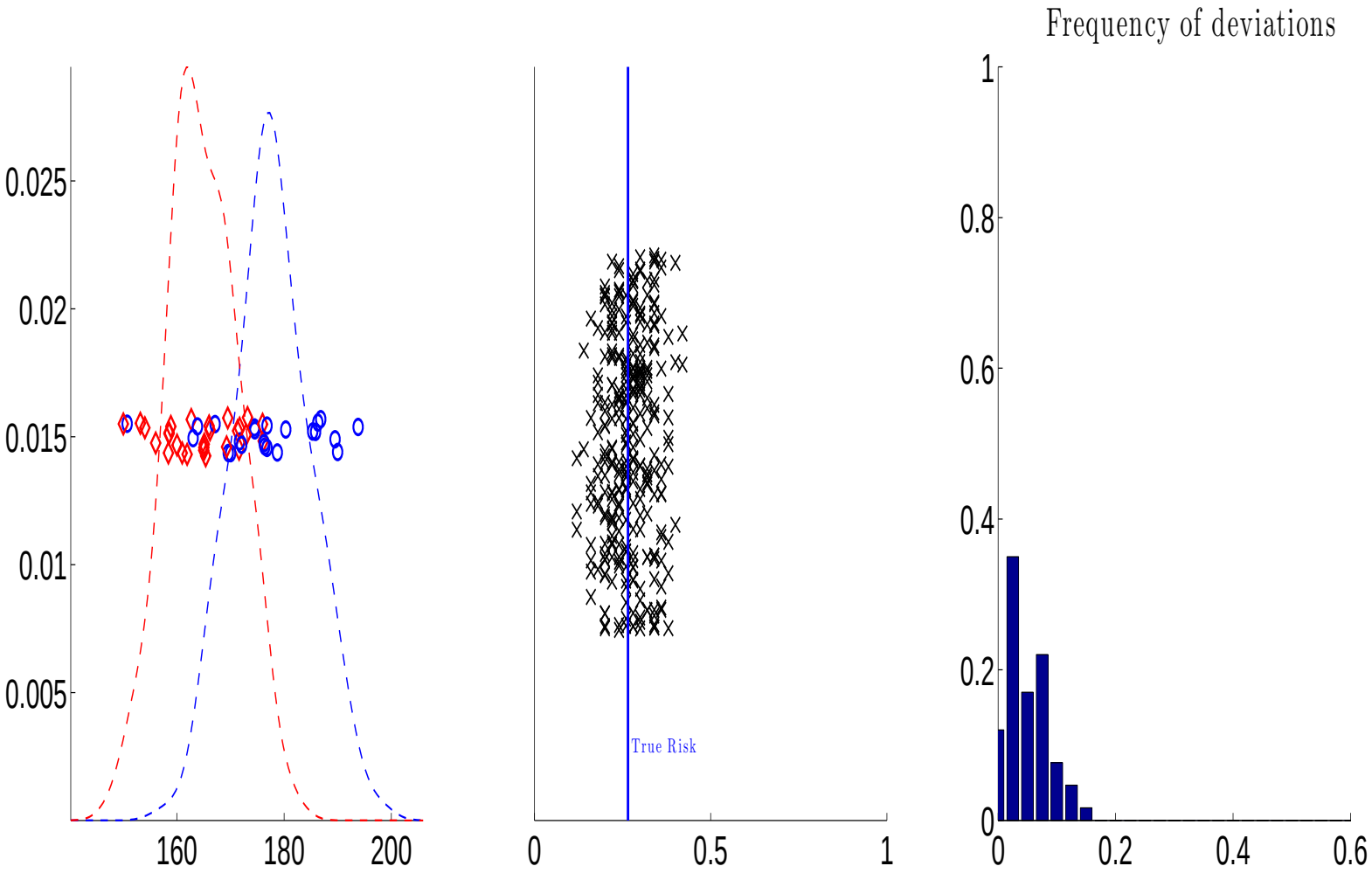
with $n = 10$ resampled 300 times

Hoeffding's Inequality



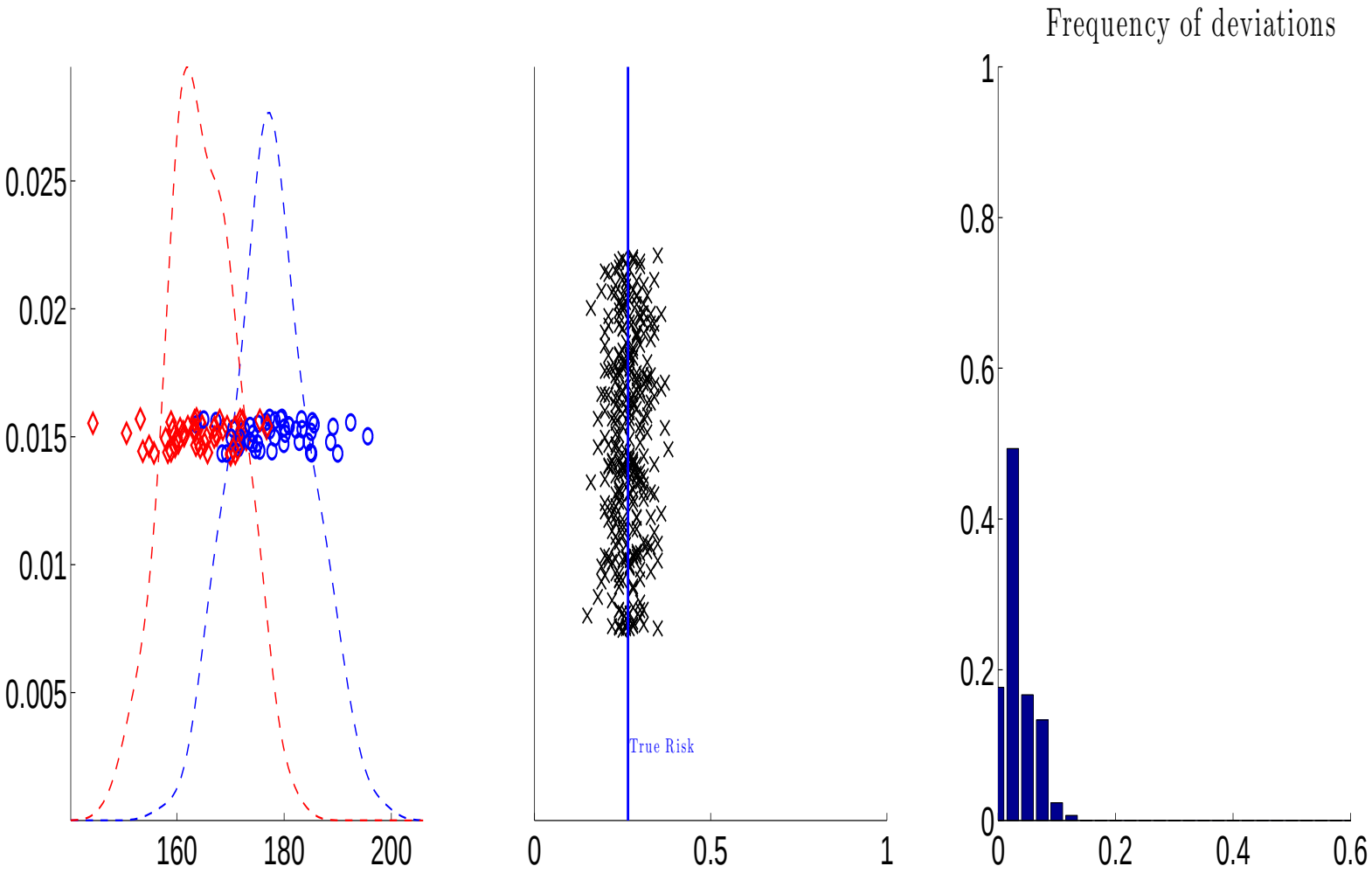
with $n = 20$ resampled 300 times

Hoeffding's Inequality



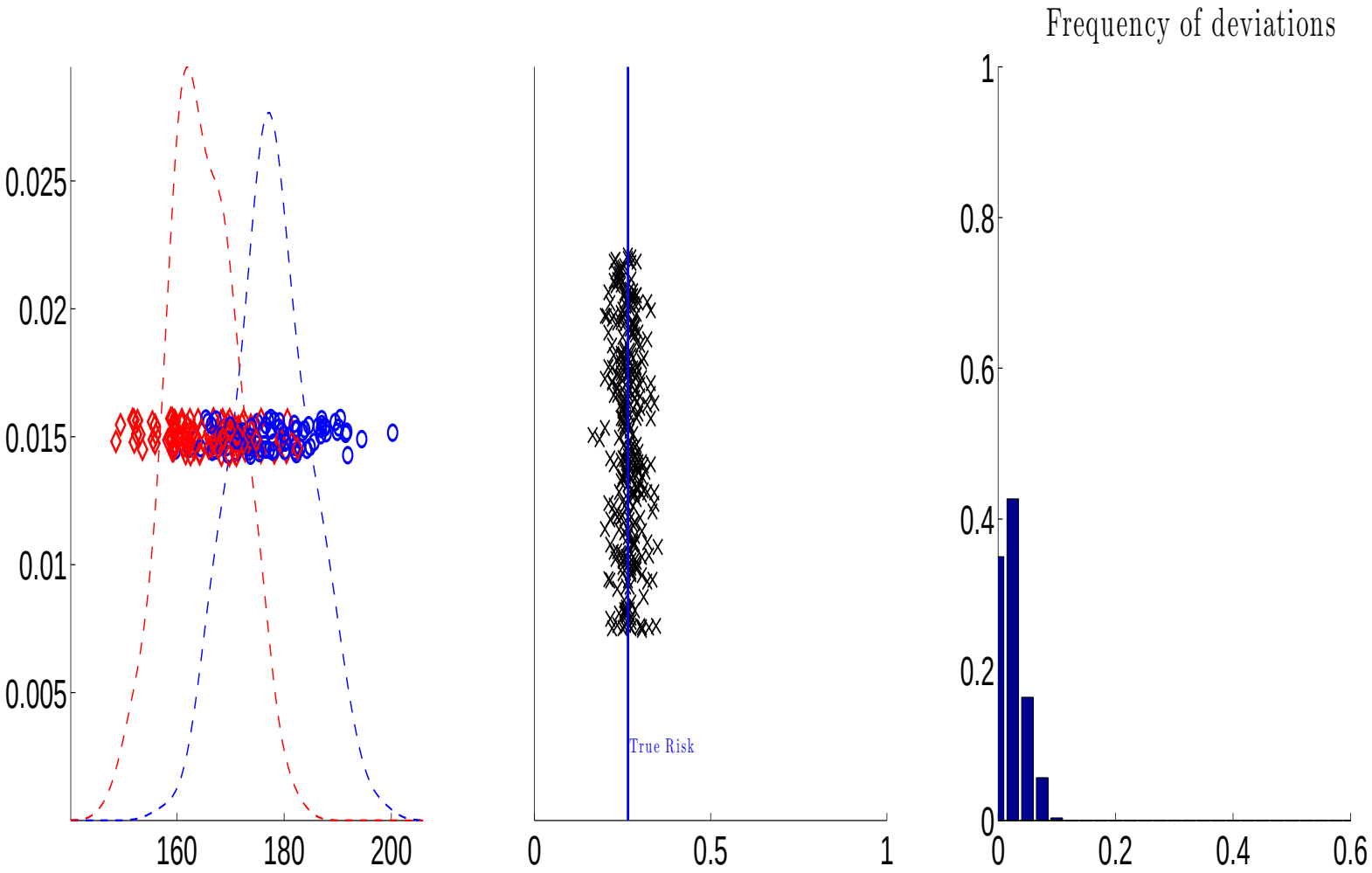
with $n = 50$ resampled 300 times

Hoeffding's Inequality



with $n = 100$ resampled 300 times

Hoeffding's Inequality



with $n = 200$ resampled 300 times

Some Proofs

Theorem 2 (Hoeffding). *Let $Z_1, \cdots, Z_n$ be n i.i.d random variables with $f(Z) \in [a, b]$. Then, $\forall \varepsilon > 0$,*

$$P\left(|P_n f - Pf| > \varepsilon\right) \leq 2e^{-\frac{2n\varepsilon^2}{(b-a)^2}}.$$

Theorem 3 (Markov). *Let $X \geq 0$ be a non-negative random variable in $\mathbb{R}$, then*

$$P\left(X \geq t\right) \leq \frac{\mathbb{E}[X]}{t}.$$

Inverting Hoeffding's Inequality

- Naturally, if

$$P\left(|P_n f - Pf| > \varepsilon\right) \leq 2e^{-\frac{2n\varepsilon^2}{(b-a)^2}}.$$

- then for $\delta > 0$,

$$P\left(|P_n f - Pf| > (b-a)\sqrt{\frac{\log\frac{2}{\delta}}{2n}}\right) \leq \delta.$$

- which is also interpreted as, with probability at least $1-\delta$,

$$|P_n f - Pf| \leq (b-a)\sqrt{\frac{\log\frac{2}{\delta}}{2n}}$$

Interpretation in terms of Risk

- Functions f take values between $a = 0$ and $b = 1$. $b - a = 1$ for all inequalities.
- For any function g, and any δ, with probability at least $1 - \delta$,

$$R(g) \leq R_n^{\text{emp}}(g) + \sqrt{\frac{\log \frac{2}{\delta}}{2n}}$$

- Note that the ***probability at least*** statement refers to **samples of size** n.

However...

- This result looks nice.
- It is, however, **not** useful directly... why?
  - Get data first, estimate g_n... gap between $R(g_n)$ and $R_n(g_n)$?
  - Define $\hat{g}$ as $\hat{g}(\mathbf{x}_i) = y_i$ and $\hat{g} = 0$ everywhere else.
  - Of course, $R(\hat{g}) \gg R_n^{\text{emp}}(\hat{g}) \stackrel{\text{def}}{=} 0$.
- Why cannot we apply directly Hoeffding's bound in this case?

Uniform Bounds

- We focus now on **uniform** deviations on the function class,

$$\sup_{f \in \mathcal{F}} \{Pf - P_n f\},$$

- Since we know that *whatever the function* g_n we choose with the sample,

$$R(g) - R_n(g_n) \leq \sup_{g \in \mathcal{G}} \{R(g) - R_n(g)\} = \sup_{f \in \mathcal{F}} \{Pf - P_n f\},$$

Obtaining Uniform Bounds

- Simple example with two functions f_1 and f_2.
- Define the two sets of n-uples,

$$C_1 = \{\{(\mathbf{x}_1, y_1), \cdots, (\mathbf{x}_n, y_n)\} \mid Pf_1 - P_n f_1 > \varepsilon\}$$

and

$$C_2 = \{\{(\mathbf{x}_1, y_1), \cdots, (\mathbf{x}_n, y_n)\} \mid Pf_2 - P_n f_2 > \varepsilon\}$$

- These sets are the "bad" sets for which empirical risk is much lower than the real risk.

Obtaining Uniform Bounds

- For each, we have the Hoeffing's inequalities **(no absolute value)**, that

$$P(C_1) \leq \delta, P(C_2) \leq \delta \text{ where } \delta = e^{-2n\varepsilon^2}.$$

- Note that whenever a n-uple is in $C_1 \cup C_2$, then either

$$Pf_1 - P_n f_1 > \varepsilon \text{ or } Pf_1 - P_n f_1 > \varepsilon.$$

- Of course, $P(C_1 \cup C_2) \leq P(C_1) + P(C_2) \leq 2\delta$.
- Thus, with probability smaller than 2δ at least one of f_1 or f_2 will be such that $Pf_1 - P_n f_1 > \varepsilon$.

Generalizing to N functions

- Consider $f_1, \cdots, f_N$ functions.
- Define the corresponding sets of n-uples, $C_1, \cdots, C_N$ with ε fixed.
- Of course,

$$P(C_1 \cup C_2 \cup \cdots \cup C_N) \leq \sum_{i=1}^{N} P(C_i)$$

- Use now Hoeffding's inequality

$$P(\exists f \in \{f_1, \cdots, f_N\} \,|\, Pf - P_n f > \varepsilon) = P\left(\bigcup_{i=1}^{N} C_i\right)$$

$$\leq \sum_{i=1}^{N} P(C_i) \leq N\delta = Ne^{-2n\varepsilon^2}$$

Error bound for finite families of functions

- We thus have that for **any** family of N functions,

$$P(\sup_{f \in \mathcal{F}} Pf - P_n f \geq \varepsilon) \leq N e^{-2n\varepsilon^2},$$

- or equivalently, that if $\mathcal{G} = \{g_1, \cdots, g_N\}$, with probability at least $1 - \delta$,

$$\forall g \in \mathcal{G}, \quad R(g) \leq R_n(g) + \sqrt{\frac{\log N + \log \frac{1}{\delta}}{2n}}$$

Estimation bound for finite families of functions

- Recall that $g^\star$ is a function in $\mathcal{G}$ such that $R(g^\star) = \min_{g\in\mathcal{G}} R(g)$.
- The inequality

$$R(g^\star) \leq R_n^{\text{emp}}(g^\star) + \sup_{g\in\mathcal{G}} \left(R(g) - R_n^{\text{emp}}(g)\right),$$

- combined with $R_n^{\text{emp}}(g^\star) - R_n^{\text{emp}}(g_n) \geq 0$ by definition of g_n, we get

$$\begin{aligned} R(g_n) = R(g_n) - R(g^\star) + R(g^\star) &\leq \underbrace{R_n^{\text{emp}}(g^\star) - R_n^{\text{emp}}(g_n)}_{\geq 0} + R(g_n) - R(g^\star) + R(g^\star) \\ &\leq 2 \sup_{g\in\mathcal{G}} |R(g) - R_n^{\text{emp}}(g)| + R(g^\star) \end{aligned}$$

- Hence, with probability at least $1-\delta$,

$$R(g_n) \leq R(g^\star) + 2\sqrt{\frac{\log N + \log \frac{2}{\delta}}{2n}}$$

Hoeffding's bound for countable families of functions

- Suppose now that we have a countable family $\mathcal{F}$
- Suppose that we assign a number $\delta(f) > 0$ to each $f \in \mathcal{F}$, which we use to set

$$P\left(|Pf - P_n f| > \sqrt{\frac{\log \frac{2}{\delta(f)}}{2n}}\right) \leq \delta(f),$$

- Using the union bound on a **countable set** (basic probability axiom),

$$P\left(\exists f \in \mathcal{F} : |P_n f - Pf| > \sqrt{\frac{\log \frac{2}{\delta(f)}}{2n}}\right) \leq \sum_{f \in \mathcal{F}} \delta(f).$$

- Let us set $\delta(f) = \rho p(f)$ with $\rho > 0$ and $\sum_{f \in \mathcal{F}} p(f) = 1$.
- Then with probability $1 - \rho$,

$$\forall f \in \mathcal{F}, Pf \leq P_n f + \sqrt{\frac{\log \frac{1}{p(f)} + \log \frac{1}{\rho}}{2n}}.$$

Hoeffding's bound for general families of functions

- Two problems:
  - Most interesting families of functions are not countable.
  - Defining the weights $p(f)$ is not so obvious.
- However, what really matters for a sample $\mathbf{z}_1, \cdots, \mathbf{z}_n$ is

$$\mathcal{F}_{\mathbf{z}_1,\cdots,\mathbf{z}_n} = \{(f(\mathbf{z}_1), f(\mathbf{z}_2), \cdots, f(\mathbf{z}_n)), \ f \in \mathcal{F}\}$$

- $\mathcal{F}_{\mathbf{z}_1,\cdots,\mathbf{z}_n}$ is a large set of binary vectors $\subset \{0,1\}^N$
- The more complex $\mathcal{F}$, the larger $\mathcal{F}_{\mathbf{z}_1,\cdots,\mathbf{z}_n}$ with maximum 2^n possible elements.

Definition 1 (Growth Function). *The growth function of $\mathcal{F}$ is equal to*

$$S_{\mathcal{F}}(n) = \sup_{(\mathbf{z}_1,\cdots,\mathbf{z}_n)} |\mathcal{F}_{\mathbf{z}_1,\cdots,\mathbf{z}_N}|$$

Vapnik-Chervonenkis

Theorem 4 (Vapnik-Chervonenkis). *For any $\delta > 0$, with probability at least $1 - \delta$,*

$$\forall g \in \mathcal{G}, R(g) \leq R_n(g) + 2\sqrt{2\frac{\log S_{\mathcal{G}}(2n) + \log \frac{2}{\delta}}{n}}$$

Definition 2 (VC Dimension). *The VC dimension of a class $\mathcal{G}$ is the largest n such that*

$$S_{\mathcal{G}}(n) = 2^n.$$

Vapnik-Chervonenkis

- The VC dimension of linear classifiers in $\mathbb{R}^d$ is $d + 1$.

Vapnik-Chervonenkis

- Given the VC dimension h of a family $\mathcal{G}$, we can prove

$$\forall g \in \mathcal{G}, R(g) \leq R_n(g) + 2\sqrt{2\frac{h \log \frac{2en}{h} + \log \frac{2}{\delta}}{n}}$$

Lemma 1 (Vapnik and Chervonenkis, Sauer, Shelah). *Let $\mathcal{G}$ be a class of functions with finite VC-dimension h. Then,*

$$\forall n \in \mathbb{N}, S_{\mathcal{G}}(n) \leq \sum_{i=0}^{h} \binom{n}{i},$$

$$\forall n \geq h, S_{\mathcal{G}}(n) \leq \left(\frac{en}{h}\right)^h.$$

- Combining with VC theorem, we obtain the result given above.
- Important thing: difference between true and empirical risks is at most of the order of

$$\sqrt{\frac{h \log n}{n}}$$